

**Chapter 13: General Solutions to Homogeneous Linear Differential Equations**

**13.2 a.** Verifying that  $\{y_1, y_2\}$  is a fundamental solution set: We have

$$y_1(x) = \cos(2x) \rightsquigarrow y_1'(x) = -2\sin(2x) \rightsquigarrow y_1''(x) = -4\cos(2x) ,$$

and

$$y_2(x) = \sin(2x) \rightsquigarrow y_2'(x) = 2\cos(2x) \rightsquigarrow y_2''(x) = -4\sin(2x) .$$

Thus,

$$y_1'' + 4y_1 = -4\cos(2x) + 4\cos(2x) = 0 ,$$

and

$$y_2'' + 4y_2 = -4\sin(2x) + 4\sin(2x) = 0 ,$$

verifying that  $\cos(2x)$  and  $\sin(2x)$  are solutions to the given differential equation. Also, it should be obvious that neither is a constant multiple of each other. Hence,  $\{\cos(2x), \sin(2x)\}$  is a fundamental set of solutions for the given differential equation.

Solving the initial-value problem: Set

$$y(x) = A\cos(2x) + B\sin(2x) . \quad (\star)$$

Applying the initial conditions and using the above derivatives, we have

$$2 = y(0) = A\cos(2 \cdot 0) + B\sin(2 \cdot 0) = A \cdot 1 + B \cdot 0 = A ,$$

and

$$6 = y'(0) = -2A\sin(2 \cdot 0) + 2B\cos(2 \cdot 0) = -2A \cdot 0 + 2B \cdot 1 = 2B .$$

So the solution to the initial-value problem is given by formula  $(\star)$  with  $A = 2$  and  $B = 6/2 = 3$ ; that is,

$$y(x) = 2\cos(2x) + 3\sin(2x) .$$

**13.2 c.** Verifying that  $\{y_1, y_2\}$  is a fundamental solution set: We have

$$y_1(x) = e^{2x} \rightsquigarrow y_1'(x) = 2e^{2x} \rightsquigarrow y_1''(x) = 4e^{2x} ,$$

and

$$y_2(x) = e^{-3x} \rightsquigarrow y_2'(x) = -3e^{-3x} \rightsquigarrow y_2''(x) = 9e^{-3x} .$$

Thus,

$$y_1'' + y_1' - 6y_1 = 4e^{2x} + 2e^{2x} - 6e^{2x} = [4 + 2 - 6]e^{2x} = 0 ,$$

and

$$y_2'' + y_2' - 6y_2 = 9e^{-3x} - 3e^{-3x} - 6e^{-3x} = [9 - 3 - 6]e^{-3x} = 0 ,$$

verifying that  $e^{2x}$  and  $e^{-3x}$  are solutions to the given differential equation. Also, it should be obvious that neither is a constant multiple of each other. Hence,  $\{e^{2x}, e^{-3x}\}$  is a fundamental set of solutions for the given differential equation.

Solving the initial-value problem: Set

$$y(x) = Ae^{2x} + Be^{-3x} . \quad (\star)$$

Applying the initial conditions and using the above derivatives, we have

$$8 = y(0) = Ae^{2 \cdot 0} + Be^{-3 \cdot 0} = A \cdot 1 + B \cdot 1 = A + B \quad ,$$

and

$$-9 = y'(0) = 2Ae^{2 \cdot 0} - 3Be^{-3 \cdot 0} - 2A \cdot 1 - 3B \cdot 1 = 2A - 3B \quad ,$$

giving us the algebraic system

$$A + B = 8 \quad \text{and} \quad 2A - 3B = -9 \quad ,$$

which can be solved many ways. For now, we'll just solve the first equation for  $B = 8 - A$ , plug that into the second equation, obtaining

$$2A - 3(8 - A) = -9 \quad \rightsquigarrow \quad 5A = 15 \quad \rightsquigarrow \quad A = \frac{15}{5} = 3 \quad ,$$

and then plug that result back into the formula for  $B$ . So the solution to the initial-value problem is given by formula  $(\star)$  with  $A = 3$  and  $B = 8 - A = 8 - 3 = 5$ ; that is,

$$y(x) = 3e^{2x} + 4e^{-3x} \quad .$$

**13.2 e.** Verifying that  $\{y_1, y_2\}$  is a fundamental solution set: We have

$$y_1(x) = x^2 \quad \rightsquigarrow \quad y_1'(x) = 2x \quad \rightsquigarrow \quad y_1''(x) = 2 \quad ,$$

and

$$y_2(x) = x^3 \quad \rightsquigarrow \quad y_2'(x) = 3x^2 \quad \rightsquigarrow \quad y_2''(x) = 6x \quad .$$

Thus,

$$\begin{aligned} x^2 y_1'' - 4x y_1' + 6y_1 &= x^2[2] - 4x[2x] + 6[x^2] \\ &= [2 - 8 + 6]x^2 = 0 \quad , \end{aligned}$$

and

$$\begin{aligned} x^2 y_2'' - 4x y_2' + 6y_2 &= x^2[6x] - 4x[3x^2] + 6[x^3] \\ &= [6 - 12 + 6]x^3 = 0 \quad , \end{aligned}$$

verifying that  $x^2$  and  $x^3$  are solutions to the given differential equation. Also, it should be obvious that neither is a constant multiple of each other. Hence,  $\{x^2, x^3\}$  is a fundamental set of solutions for the given differential equation.

Solving the initial-value problem: Set

$$y(x) = Ax^2 + Bx^3 \quad . \tag{\star}$$

Applying the initial conditions and using the above derivatives, we have

$$0 = y(1) = A \cdot 1^2 + B \cdot 2^3 = A + B \quad ,$$

and

$$4 = y'(1) = A \cdot 2 \cdot 1 + B \cdot 3 \cdot 1^2 = 2A + 3B \quad .$$

So,  $A + B = 0$  and  $2A + 3B = 4$

$$\hookrightarrow B = -A \quad \text{and} \quad 4 = 2A + 3B = 2A + 3(-A) = -A$$

$$\hookrightarrow B = -A = 4 \quad \text{and} \quad A = -4 .$$

So the solution to the initial-value problem is given by formula (★) with  $A = -4$  and  $B = 4$ ; that is,

$$y(x) = -4x^2 + 4x^3 .$$

**13.2 g.** Verifying that  $\{y_1, y_2\}$  is a fundamental solution set: We have

$$y_1(x) = x \rightsquigarrow y_1'(x) = 1 \rightsquigarrow y_1''(x) = 0 ,$$

and

$$y_2(x) = x \ln |x| \rightsquigarrow y_2'(x) = \ln |x| + 1 \rightsquigarrow y_2''(x) = x^{-1} .$$

Thus,

$$\begin{aligned} x^2 y_1'' - x y_1' + y_1 &= x^2[0] - x[1] + [x] \\ &= -x + x = 0 , \end{aligned}$$

and

$$\begin{aligned} x^2 y_2'' - x y_2' + y_2 &= x^2[x^{-1}] - x[\ln |x| + 1] + [x \ln |x|] \\ &= x - x \ln |x| - x + x \ln |x| = 0 , \end{aligned}$$

verifying that  $x$  and  $x \ln |x|$  are solutions to the given differential equation. Also, it should be obvious that neither is a constant multiple of each other. Hence,  $\{x, x \ln |x|\}$  is a fundamental set of solutions for the given differential equation (on  $(0, \infty)$ ).

Solving the initial-value problem: Set

$$y(x) = Ax + Bx \ln |x| . \tag{★}$$

Applying the initial conditions and using the above derivatives, we have

$$5 = y(1) = A[1] + B[1 \ln |1|] = A + B \cdot 0 = A ,$$

and

$$3 = y'(1) = A[1] + B[\ln |1| + 1] = A + B \cdot 1 = A + B .$$

So,

$$A = 5 \quad \text{and} \quad A + B = 3$$

$$\hookrightarrow A = 5 \quad \text{and} \quad B = 3 - A = 3 - 5 = -2 .$$

So the solution to the initial-value problem is given by formula (★) with  $A = 5$  and  $B = -2$ ; that is,

$$y(x) = 5x - 2x \ln |x| .$$

**13.2 i.** Verifying that  $\{y_1, y_2\}$  is a fundamental solution set: We have

$$y_1(x) = x^2 - 1 \rightsquigarrow y_1'(x) = 2x \rightsquigarrow y_1''(x) = 2 ,$$

and

$$y_2(x) = x + 1 \quad \rightsquigarrow \quad y_2'(x) = 1 \quad \rightsquigarrow \quad y_2''(x) = 0 \quad .$$

Thus,

$$\begin{aligned} (x+1)^2 y_1'' - 2(x+1)y_1' + 2y_1 &= (x+1)^2 [2] - 2(x+1)[2x] + 2[x^2 - 1] \\ &= [2x^2 + 4x + 2] - [4x^2 + 4x] + [2x^2 - 2] \\ &= [2 - 4 + 2]x^2 + [4 - 4]x + [2 - 2] = 0 \quad , \end{aligned}$$

and

$$\begin{aligned} (x+1)^2 y_2'' - 2(x+1)y_2' + 2y_2 &= (x+1)^2 [0] - 2(x+1)[1] + 2[x+1] \\ &= 2(x+1) - 2(x+1) = 0 \quad , \end{aligned}$$

verifying that  $x^2 - 1$  and  $x + 1$  are solutions to the given differential equation. Also, it should be obvious that neither is a constant multiple of each other. Hence,  $\{x^2 - 1, x + 1\}$  is a fundamental set of solutions for the given differential equation.

Solving the initial-value problem: Set

$$y(x) = A[x^2 - 1] + B[x + 1] \quad . \quad (\star)$$

Applying the initial conditions and using the above derivatives, we have

$$0 = y(0) = A[0^2 - 1] + B[0 + 1] = -A + B \quad ,$$

and

$$4 = y'(0) = A[2 \cdot 0] + B[1] = B \quad .$$

So,

$$-A + B = 0 \quad \text{and} \quad B = 4$$

$\hookrightarrow$

$$A = B = 4 \quad \text{and} \quad B = 4 \quad .$$

So the solution to the initial-value problem is given by formula  $(\star)$  with  $A = 4$  and  $B = 4$ ; that is,

$$y(x) = 4[x^2 - 1] + 4[x + 1] = 4x^2 - 4 + 4x + 4 = 4x^2 + 4x \quad .$$

**13.3 a.** The equation is

$$ay'' + by' + cy = 0 \quad \text{with} \quad a = x^2 \quad , \quad b = -4x \quad \text{and} \quad c = 6 \quad .$$

Each coefficient is continuous on  $(-\infty, \infty)$ , but the first,  $a$  is 0 if and only if  $x = 0$ . So the interval must not contain  $x = 0$ , and the largest such interval that also contains  $x_0 = 1$  is  $(0, \infty)$ .

**13.3 b.** In this case,

$$y(x) = c_1x^2 + c_2x^3 \quad \text{and} \quad y'(x) = 2c_1x + 3c_2x^2 .$$

Applying the initial conditions, we get

$$0 = y(0) = c_1 \cdot 0^2 + c_2 \cdot 0^3 = 0 ,$$

and

$$-4 = y'(0) = 2c_1 \cdot 0 + 3c_2 \cdot 0^2 = 0 .$$

So, no matter what  $c_1$  and  $c_2$  are,  $y = c_1x^2 + c_2x^3$  and its derivative will always be 0 when  $x = 0$ , and, hence  $c_1$  and  $c_2$  cannot be chosen so that  $y(0)$  or  $y'(0)$  is nonzero.

Theorem 13.3 requires that the point  $x_0$  at which initial values are given be in an interval  $(\alpha, \beta)$  over which the coefficients of the differential equation are continuous with the first one (the  $a = x^2$ , here) never being zero. Hence, the theorem requires that the coefficients be continuous and  $a \neq 0$  at the point  $x_0$  at which initial values are given. As noted in the first part of this exercise, while the coefficients are continuous at  $x = 0$ , the first coefficient is zero at  $x = 0$ . So theorem 13.3 does not apply here.

**13.5 a.** Verifying that  $\{y_1, y_2, y_3\}$  is a fundamental solution set: We have

$$y_1(x) = 1 \rightsquigarrow y_1'(x) = 0 \rightsquigarrow y_1''(x) = 0 \rightsquigarrow y_1'''(x) = 0 ,$$

and

$$y_2(x) = \cos(2x) \rightsquigarrow y_2'(x) = -2 \sin(2x)$$

$$\iff y_2''(x) = -4 \cos(2x) \rightsquigarrow y_2'''(x) = 8 \sin(2x) ,$$

and

$$y_3(x) = \sin(2x) \rightsquigarrow y_3'(x) = 2 \cos(2x)$$

$$\iff y_3''(x) = -4 \sin(2x) \rightsquigarrow y_3'''(x) = -8 \cos(2x) .$$

Thus,

$$y_1''' + 4y_1' = 0 + 4 \cdot 0 = 0 ,$$

$$y_2''' + 4y_2' = 8 \sin(2x) + 4[-2 \sin(2x)] = [8 - 8] \sin(2x) = 0 ,$$

and

$$y_3''' + 4y_3' = -8 \cos(2x) + 4[2 \cos(2x)] = [-8 + 8] \cos(2x) = 0 ,$$

verifying that  $1$ ,  $\cos(2x)$  and  $\sin(2x)$  are solutions to the given differential equation. To confirm that they form a fundamental set of solutions for this third-order equation, we must show that they form a linearly independent set. To do that, first form the corresponding Wronskian,

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix} = \begin{vmatrix} 1 & \cos(2x) & \sin(2x) \\ 0 & -2 \sin(2x) & 2 \cos(2x) \\ 0 & -4 \cos(2x) & -4 \sin(2x) \end{vmatrix} .$$

Plugging in a convenient value for  $x$ , say  $x = \pi/4$  so that  $2x = \pi/2$ , we have

$$W\left(\frac{\pi}{4}\right) = \begin{vmatrix} 1 & \cos\left(\frac{\pi}{2}\right) & \sin\left(\frac{\pi}{2}\right) \\ 0 & -2\sin\left(\frac{\pi}{2}\right) & 2\cos\left(\frac{\pi}{2}\right) \\ 0 & -4\cos\left(\frac{\pi}{2}\right) & -4\sin\left(\frac{\pi}{2}\right) \end{vmatrix} = \begin{vmatrix} 1 & 0 & 1 \\ 0 & -2 & 0 \\ 0 & 0 & -4 \end{vmatrix} = 8 \neq 0 .$$

Since the Wronskian is nonzero at one point, theorem 13.6 assures us that  $\{1, \cos(2x), \sin(2x)\}$  is linearly independent and a fundamental set of solutions for this differential equation.

Solving the initial-value problem: Set

$$y(x) = A \cdot 1 + B \cos(2x) + C \sin(2x) . \quad (\star)$$

Applying the initial conditions and using the above derivatives, we have

$$3 = y(0) = A \cdot 1 + B \cos(2 \cdot 0) + C \sin(2 \cdot 0) = A + B ,$$

$$8 = y'(0) = A \cdot 0 + B[-2 \sin(2 \cdot 0)] + C[2 \cos(2 \cdot 0)] = 2C .$$

and

$$4 = y''(0) = A \cdot 0 + B[-4 \cos(2 \cdot 0)] + C[-2 \sin(2 \cdot 0)] = -4B .$$

So, the solution to the initial-value problem is  $(\star)$  with

$$C = \frac{8}{2} = 4 \quad , \quad B = \frac{4}{-4} = -1$$

and

$$A = 3 - B = 3 - (-1) = 4 .$$

That is,

$$y(x) = 4 - \cos(2x) + 4 \sin(2x)$$

**13.5 c.** Verifying that  $\{y_1, y_2, y_3, y_4\}$  is a fundamental solution set: We have

$$y_1(x) = \cos(x) \quad \rightsquigarrow \quad y_1'(x) = -\sin(x)$$

$$\hookrightarrow \quad y_1''(x) = -\cos(x) \quad \rightsquigarrow \quad y_1'''(x) = \sin(x)$$

$$\hookrightarrow \quad y_1^{(4)}(x) = \cos(x) ,$$

and

$$y_2(x) = \sin(x) \quad \rightsquigarrow \quad y_2'(x) = \cos(x)$$

$$\hookrightarrow \quad y_2''(x) = -\sin(x) \quad y_2'''(x) = -\cos(x)$$

$$\hookrightarrow \quad y_2^{(4)}(x) = \sin(x) .$$

and

$$y_3(x) = \cosh(x) \rightsquigarrow y_3'(x) = \sinh(x)$$

$$\hookrightarrow y_3''(x) = \cosh(x) \rightsquigarrow y_3'''(x) = \sinh(x)$$

$$\hookrightarrow y_3^{(4)}(x) = \cosh(x) \text{ ,}$$

and

$$y_4(x) = \sinh(x) \rightsquigarrow y_4'(x) = \cosh(x)$$

$$\hookrightarrow y_4''(x) = \sinh(x) \rightsquigarrow y_4'''(x) = \cosh(x)$$

$$\hookrightarrow y_4^{(4)}(x) = \sinh(x) \text{ .}$$

Thus,

$$y_1^{(4)} - y_1 = \cos(x) - \cos(x) = 0 \text{ ,}$$

$$y_2^{(4)} - y_2 = \sin(x) - \sin(x) = 0 \text{ ,}$$

$$y_3^{(4)} - y_3 = \cosh(x) - \cosh(x) = 0 \text{ ,}$$

and

$$y_4^{(4)} - y_4 = \sinh(x) - \sinh(x) = 0 \text{ ,}$$

verifying that these four functions are solutions to the given differential equation. To confirm that they form a fundamental set of solutions for this fourth-order equation, we must show that they form a linearly independent set. To do that, first form the corresponding Wronskian,

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1' & y_2' & y_3' & y_4' \\ y_1'' & y_2'' & y_3'' & y_4'' \\ y_1''' & y_2''' & y_3''' & y_4''' \end{vmatrix} = \begin{vmatrix} \cos(x) & \sin(x) & \cosh(x) & \sinh(x) \\ -\sin(x) & \cos(x) & \sinh(x) & \cosh(x) \\ -\cos(x) & -\sin(x) & \cosh(x) & \sinh(x) \\ \sin(x) & -\cos(x) & \sinh(x) & \cosh(x) \end{vmatrix} \text{ .}$$

Plugging in a convenient value for  $x$ , say  $x = 0$ , we have

$$\begin{aligned} W(0) &= \begin{vmatrix} \cos(0) & \sin(0) & \cosh(0) & \sinh(0) \\ -\sin(0) & \cos(0) & \sinh(0) & \cosh(0) \\ -\cos(0) & -\sin(0) & \cosh(0) & \sinh(0) \\ \sin(0) & -\cos(0) & \sinh(0) & \cosh(0) \end{vmatrix} \\ &= \begin{vmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{vmatrix} \\ &= 1 \cdot \begin{vmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{vmatrix} + 1 \cdot \begin{vmatrix} 0 & 1 & 1 \\ -1 & 0 & 0 \\ 0 & -1 & 1 \end{vmatrix} = 1 \cdot 2 + 1 \cdot 2 \neq 0 \text{ .} \end{aligned}$$

Since the Wronskian is nonzero at one point, theorem 13.6 assures us that

$$\{\cos(x), \sin(x), \cosh(x), \sinh(x)\}$$

is a fundamental set of solutions for this differential equation.

Solving the initial-value problem: Set

$$y(x) = A \cos(x) + B \sin(x) + C \cosh(x) + \sinh(x) \quad . \quad (\star)$$

Applying the initial conditions and using the above derivatives, we have

$$0 = y(0) = A \cos(0) + B \sin(0) + C \cosh(0) + \sinh(0) = A + C \quad ,$$

$$4 = y'(0) = -A \sin(0) + B \cos(0) + C \sinh(0) + D \cosh(0) = B + D \quad ,$$

$$0 = y''(0) = -A \cos(0) - B \sin(0) + C \cosh(0) + \sinh(0) = -A + C$$

and

$$0 = y'''(0) = A \sin(0) - B \cos(0) + C \sinh(0) + D \cosh(0) = -B + D \quad .$$

Solving for  $A$  and  $C$  is easy:

$$0 = A + C \quad \text{and} \quad 0 = -A + C$$

$$\hookrightarrow C = -A \quad \text{and} \quad 0 = -A + C = -A - A = -2A$$

$$\hookrightarrow C = -A = -\frac{0}{-2} = 0 \quad \text{and} \quad A = \frac{0}{-2} = 0 \quad .$$

For  $B$  and  $D$ :

$$4 = B + D \quad \text{and} \quad 0 = -B + D$$

$$\hookrightarrow 4 = B + D \quad \text{and} \quad D = B$$

$$\hookrightarrow 4 = B + B = 2B \quad \text{and} \quad D = B$$

$$\hookrightarrow B = \frac{4}{2} = 2 \quad \text{and} \quad D = B = 2 \quad .$$

Plugging these values into  $(\star)$  then gives the solution,

$$\begin{aligned} y(x) &= 0 \cos(x) + 2 \sin(x) + 0 \cosh(x) + 2 \sinh(x) \\ &= 2 \sin(x) + 2 \sinh(x) \quad . \end{aligned}$$

**13.6 a.** Setting  $y = e^{rx} \rightsquigarrow y' = r e^{rx} \rightsquigarrow y'' = r^2 e^{rx}$  ,  
we have

$$0 = y'' - 4y = r^2 e^{rx} - 4e^{rx} = [r^2 - 4] e^{rx} \quad .$$

Since  $e^{rx} \neq 0$  for all  $x$  , it follows that

$$0 = r^2 - 4 \quad .$$



But

$$0 = r^2 - 4 \rightsquigarrow r^2 = 4 \rightsquigarrow r = \pm\sqrt{4} = \pm 2 .$$

So  $e^{rx}$  is a solution to the differential equation if  $r = 2$  or  $r = -2$ . That is,  $\{e^{2x}, e^{-2x}\}$  is a pair of solutions to the given second-order, homogeneous linear differential equation. Clearly, neither is a constant multiple of each other. So, in fact, this is a fundamental set of solutions, and

$$y(x) = c_1 e^{2x} + c_2 e^{-2x} \quad (\star)$$

is a general solution to the differential equation.

For the initial-value problem: We have

$$y(x) = c_1 e^{2x} + c_2 e^{-2x} \rightsquigarrow y'(x) = 2c_1 e^{2x} - 2c_2 e^{-2x} .$$

Applying the initial conditions:

$$1 = y(0) = c_1 e^{2 \cdot 0} + c_2 e^{-2 \cdot 0} = c_1 + c_2 ,$$

and

$$0 = y'(0) = 2c_1 e^{2 \cdot 0} - 2c_2 e^{-2 \cdot 0} = 2c_1 - 2c_2 .$$

So,

$$1 = c_1 + c_2 \quad \text{and} \quad 0 = 2c_1 - 2c_2$$

$$\hookrightarrow 1 = c_1 + c_2 \quad \text{and} \quad c_2 = c_1$$

$$\hookrightarrow 1 = c_1 + c_2 = c_1 + c_1 = 2c_1 \quad \text{and} \quad c_2 = c_1$$

$$\hookrightarrow c_1 = \frac{1}{2} \quad \text{and} \quad c_2 = c_1 = \frac{1}{2} .$$

Plugging these values into  $(\star)$  then gives the solution,

$$y(x) = \frac{1}{2} e^{2x} + \frac{1}{2} e^{-2x} .$$

**13.6 c.** Setting  $y = e^{rx} \rightsquigarrow y' = r e^{rx} \rightsquigarrow y'' = r^2 e^{rx}$ , we have

$$0 = y'' - 10y' + 9y = r^2 e^{rx} - 10r e^{rx} + 9e^{rx} = [r^2 - 10r + 9] e^{rx} .$$

Dividing out  $e^{rx}$  and factoring<sup>1</sup> gives

$$0 = r^2 - 10r + 9 = (r - 1)(r - 9)$$

$$\hookrightarrow r = 1 \quad \text{or} \quad r = 9 .$$

So  $e^{rx}$  is a solution to the differential equation if  $r = 1$  or  $r = 9$ . That is,  $\{e^{1x}, e^{9x}\}$  is a pair of solutions to the given second-order, homogeneous linear differential equation.

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<sup>1</sup> Or you can use the quadratic formula to find  $r$ .

Clearly, neither is a constant multiple of each other. So, in fact, this is a fundamental set of solutions, and

$$y(x) = c_1 e^x + c_2 e^{9x} \quad (\star)$$

is a general solution to the differential equation.

For the initial-value problem: We have

$$y(x) = c_1 e^x + c_2 e^{9x} \quad \rightsquigarrow \quad y'(x) = c_1 e^{2x} + 9c_2 e^{9x} \quad .$$

Applying the initial conditions:

$$8 = y(0) = c_1 e^0 + c_2 e^{9 \cdot 0} = c_1 + c_2 \quad ,$$

and

$$-24 = y'(0) = c_1 e^{2 \cdot 0} + 9c_2 e^{9 \cdot 0} = c_1 + 9c_2 \quad .$$

So,

$$8 = c_1 + c_2 \quad \text{and} \quad -24 = c_1 + 9c_2$$

$$\hookrightarrow c_2 = 8 - c_1 \quad \text{and} \quad -24 = c_1 + 9[8 - c_1] = 72 - 8c_1$$

$$\hookrightarrow c_2 = 8 - c_1 \quad \text{and} \quad c_1 = \frac{72 + 24}{8} = 12$$

$$\hookrightarrow c_2 = 8 - 12 = -4 \quad \text{and} \quad c_1 = 12 \quad .$$

Plugging these values into  $(\star)$  then gives the solution,

$$y(x) = 12e^x - 4e^{9x} \quad .$$

**13.7 a.** Setting  $y = e^{rx} \rightsquigarrow y' = r e^{rx} \rightsquigarrow y'' = r^2 e^{rx} \rightsquigarrow y''' = r^3 e^{rx}$ , we have

$$0 = y''' - 9y' = r^3 e^{rx} - 9r e^{rx} = [r^3 - 9r] e^{rx} \quad .$$

Dividing out  $e^{rx}$  and factoring gives

$$0 = r^3 - 9r = r(r^2 - 9) = r(r - 3)(r + 3)$$

$$\hookrightarrow r = 0 \quad \text{or} \quad r = 3 \quad \text{or} \quad r = -3 \quad .$$

So  $e^{rx}$  is a solution to the differential equation if  $r = 0$ ,  $r = 3$  or  $r = -3$ . That is,  $\{e^{0x} = 1, e^{3x}, e^{-3x}\}$  is a set of three solutions to the given third-order, homogeneous linear differential equation. The corresponding Wronskian is

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix} = \begin{vmatrix} 1 & e^{3x} & e^{-3x} \\ 0 & 3e^{3x} & -3e^{-3x} \\ 0 & 9e^{3x} & 9e^{-3x} \end{vmatrix} \quad .$$

Plugging in a convenient value for  $x$ , say  $x = 0$  so that  $e^{\pm 3x} = 1$ , we have

$$W(0) = \begin{vmatrix} 1 & 1 & 1 \\ 0 & 3 & -3 \\ 0 & 9 & 9 \end{vmatrix} = 1 \cdot [(3)(9) - (-3)(9)] = 36 \neq 0 \quad .$$

Since the Wronskian is nonzero at one point, theorem 13.6 assures us that  $\{1, e^{3x}, e^{-3x}\}$  is a fundamental set of solutions for this differential equation, and the corresponding general solution is

$$y(x) = c_1 + c_2 e^{3x} + c_3 e^{-3x} .$$

**13.9 a i.** If  $\{y_1, y_2\}$  was a linearly dependent pair on the entire real line, then there would be a single constant  $c$  such that  $y_2(x) = cy_1(x)$  at every point  $x$  where  $y_1(x) \neq 0$ , which in turn, means that there would be a single constant  $c$  such that, whenever  $y(x) \neq 0$ ,

$$\frac{y_2(x)}{y_1(x)} = c$$

But then

$$c = \frac{y_2(x)}{y_1(x)} = \begin{cases} \frac{x^2}{-x^2} & \text{if } x < 0 \\ \frac{3x^2}{x^2} & \text{if } 0 < x \end{cases} = \begin{cases} -1 & \text{if } x < 0 \\ 3 & \text{if } 0 < x \end{cases} .$$

So there isn't a single such constant  $c$ . Hence,  $\{y_1, y_2\}$  is not linearly dependent on the entire real line.

**13.9 a ii.** If  $x < 0$ ,

$$\begin{aligned} W(x) &= \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = \begin{vmatrix} -x^2 & x^2 \\ -2x & 2x \end{vmatrix} \\ &= (-x^2)(2x) - (x^2)(-2x) = -2x^3 + 2x^3 = 0 . \end{aligned}$$

If  $0 < x$ ,

$$\begin{aligned} W(x) &= \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = \begin{vmatrix} x^2 & 3x^2 \\ 2x & 6x \end{vmatrix} \\ &= (x^2)(6x) - (3x^2)(2x) = 6x^3 - 6x^3 = 0 . \end{aligned}$$

If  $x = 0$ , then the derivatives would have to be computed using the basic limit definition (they do exist). However, no matter what they end up being,

$$W(0) = \begin{vmatrix} y_1(0) & y_2(0) \\ y_1'(0) & y_2'(0) \end{vmatrix} = \begin{vmatrix} 0 & 0 \\ y_1'(0) & y_2'(0) \end{vmatrix} = 0 .$$

**13.9 b.** For that theorem to apply,  $\{y_1, y_2\}$  must be a pair of solutions to some differential equation of the form

$$ay'' + by' + cy = 0$$

where  $a$ ,  $b$  and  $c$  are continuous functions on  $(-\infty, \infty)$  and with  $a$  never being zero on that interval. Obviously,  $\{y_1, y_2\}$  is not a pair of solutions to any such differential equation.

**13.9 c.** From the first part of this exercise, we know

$$y_2(x) = (-1)y_1(x) \quad \text{for } x < 0 ,$$

telling us that  $\{y_1, y_2\}$  is linearly dependent on  $(-\infty, 0)$  or any subinterval of  $(-\infty, 0)$ .

Also, we have

$$y_2(x) = (3)y_1(x) \quad \text{for } x > 0 ,$$

telling us that  $\{y_1, y_2\}$  is linearly dependent on  $(0, \infty)$  or any subinterval of  $(0, \infty)$ .